

19.2.0 ENGINEERING MATHEMATICS II

19.2.01 Introduction

This module unit is designed to equip the trainee with the knowledge, skills and attitudes to apply Mathematical skills in their trade area.

The trainee will use Advanced Mathematical tables and non-programmable scientific calculator. Suggested teaching/learning activities and resources, and evaluation methods are listed at the end of the unit.

19.2.02 General Objectives

At the end of this module unit, the trainee should be able to: -

- Understand mathematical techniques relevant to electrical engineering
- Apply mathematical techniques relevant to electrical engineering
- Appreciate the role of Mathematics in everyday life

19.2.03 Module Unit Summary and Time Allocation

Engineering Mathematics II

Code	Sub-Module Unit	Content	HRS
19.2.1	Vector Theory I	<ul style="list-style-type: none">Vector algebra and theoremsDot and Cross productsGradient, Divergence and Curl operatorsApplication	10
19.2.2	Matrices I	<ul style="list-style-type: none">Matrix operationsDeterminantsInverse of 3x3 matrixSolution of simultaneous equations	8
19.2.3	Ordinary Differential Equations	<ul style="list-style-type: none">Formation and solution of 1st differential equations2nd order linear differential equations with constant coefficientD-operatorSeries solutionsApplication of ordinary differential equation	10

19.2.4	Partial Differentiation	<ul style="list-style-type: none"> • Definition of partial derivatives • Derivation of a function of two or more variables • Problem solving • Stationary points of functions of two variables 	8
19.2.5	Laplace transforms	<ul style="list-style-type: none"> • Definition • Properties of Laplace transforms • Inverse transforms • Application of Taylor's theorem to obtain power series • Use of Maclaurin's theorem to obtain power series • Application of Taylor's theorem in numerical work. 	10
19.2.6	Power series	<ul style="list-style-type: none"> • Definition of power series • Taylor's Theorem • Maclaurin's theorem • Application of Taylor's theorem • Application of Maclaurin's theorem • Application of Maclaurin's theorem in numerical work. 	6
19.2.7	Statistics	<ul style="list-style-type: none"> • Data organization and presentation • Measures of central tendencies • Measures of dispersion • Skewness • Coefficient of skewness • Regression lines • Correlation and regression 	6
19.2.8	Probability	<ul style="list-style-type: none"> • Definition • Laws of probability • Probability distribution • Mathematical expectation • Sampling distribution 	6
Total Time			64

19.2.1	VECTOR S THEORY I	19.2.2	MATRICES I
	Theory	19.2.2T0	<i>Specific Objectives</i> By the end of the sub-module unit, the trainee should be able to:
19.2.1T0	<i>Specific Objectives</i> By the end of the sub-module unit, the trainee should able to:	a)	perform matrix operations
	a) define vector theorems	b)	determine the determinant of a 3x3 matrix using co-factor method and Sirus rule.
	b) solve problems involving the dot and cross products.	c)	determine the inverse of a 3x3 matrix
	c) define gradient, divergence and curl operators	d)	apply matrices in solving linear simultaneous equations in 3 unknowns.
	d) solve problems involving gradient, divergence and curl operators.		
	<i>Content</i>	19.2.2T1	<i>Content</i> Performing matrix operation
19.2.1T1	Definition of a vector and scalar	19.2.2T2	Determination of the determinant of a 3x3 matrix using:
19.2.1T2	Distinguish between vector and scalar quantities	i)	Co-factor method
19.2.1T3	Vector theorems	ii)	Sirus Rule
	i) Resolution of vector	19.2.2T3	Determination of the inverse of a 3x3 matrix
	ii) Proof of the Ratio theorem	i)	Adjoint and determinant
	iii) Use of the Ratio theorem	ii)	Augmented matrix and row reduction
	iv) Dot and cross products	19.2.2T4	Solution of linear simultaneous equations in 3 unknowns.
19.2.1T4	Problems involving dot and cross products of vector		
19.2.1T5	Definition of the operators gradient, divergence and curl		
19.2.1T6	Problems involving gradient, divergence and curl operators		

19.2.3	ORDINARY DIFFERENTIAL EQUATIONS		ii) R-L-C circuits
	Theory	19.2.4	PARTIAL DIFFERENTIATION
	Theory		Theory
19.2.3T0	<i>Specific Objectives</i> By the end of the sub-module unit, the trainee should be able to:	19.2.4T0	<i>Specific Objectives</i> By the end of the sub-module unit, the trainee should be able to:
	a) Form and solve 1 st order differential equation		a) define partial derivative of a function of two variables.
	b) form and solve 2 nd order linear ordinary differential equations		b) differentiate a function of two variables or more.
	c) apply the D- operator method to solve differential equations		c) solve problems involving small changes or errors using partial derivatives.
	d) apply 1 st order and 2 nd order linear differential equations in electrical problems.		d) find stationary points of functions of two variables.
	<i>Content</i>		<i>Content</i>
19.2.3T1	Formation of 1 st order linear differential equations	19.2.4T1	Definition of partial derivatives of two variables.
19.2.3T2	Solution of differential equations	19.2.4T2	Differentiation of a function of two variables or more.
	i) 1 st order variable separable	19.2.4T3	Solution of problems involving small changes using partial derivatives.
	ii) 1st order homogenous	19.2.4T4	Finding stationary points of functions of two variables.
	iii) 1st order linear		
19.2.3T3	2nd order by the method of determination of coefficients		
19.2.3T4	solution to 2nd order differential equations		
19.2.3T5	D-operator method		
	i) Simultaneous differential equations		
	ii) Series method		
19.2.3T6	Application of differential equations		
	i) Control systems		

19.2.5 **LAPLACE TRANSFORMS**

Theory

19.2.5T0 *Specific Objectives*
By the end of the sub-module unit, the trainee should able to:

- a) define the Laplace transform of a function
- b) use simple properties of Laplace transforms
- c) determine the inverse Laplace transforms of simple forms using partial fractions
- d) use Laplace transforms to solve ordinary differential equations and simultaneous differential equations with constant coefficients and given initial conditions.
- e) Apply Laplace transforms in electrical engineering

Content

- 19.2.5T1 Definition of the Laplace transform of a function
- i) Deriving the Laplace transforms of simple functions
 - ii) Laplace transform of elementary functions
 - iii) Inference of linearity properties
 - iv) Use of list of standard transforms

19.2.5TT2 Using simple properties of Laplace transforms

- i) Derivations of Laplace transforms of $F(t) e^{-at}$
- ii) Statement of initial and final value theorems for simple
- iii) Derivation of the Laplace transforms of the first and second derivatives from definition.

19.2.5T3 Determination of the inverse Laplace transforms of simple transforms using a list of transforms and partial fractions.

- i) Definition of inverse Laplace transform
- ii) Determination of inverse Laplace transforms of simple forms using a list of standard forms.
- iii) Determination of partial fractions for expressions up to degree three in the denominator including cases of linear and quadratic repeated factors.
- iv) Determination of inverse Laplace transforms of forms using partial fractions and a list of standard transforms.

19.2.5T4 Using Laplace transforms to solve:

- i) Differential equations and simultaneous

- equations with constant coefficients and given initial conditions.
- ii) Application of theorem for the Laplace transforms
- iii) Evaluations of Laplace transform using a small stock of transform key pair

$$e^{-s} H(t) = \frac{1}{P + X} - \text{Re}^s \text{Re } p$$

- iv) Application of Laplace transforms to impulse response problems.
- Using transfer transforms.
 - Setting out initial value problems.
- v) Application of Laplace transforms to switching problems.

- c) deduce Maclaurin's theorem from Taylor's theorem.
- d) apply Taylor's theorem to obtain power series
- e) apply Maclaurin's theorem to obtain power series
- f) apply Maclaurin's theorem in numerical work.

Content

- 19.2.6T1 Explanation of the term power series.
- 19.2.6T2 Statement of Taylor's Theorem.
- 19.2.6T3 Deduction of Maclaurin's theorem from Taylor's theorem.
- 19.2.6T4 Application of Taylor's theorem to obtain power series
- 19.2.6T5 Use of Maclaurin's theorem to obtain power series.
- 19.2.6T6 Application of Taylor's theorem in numerical work.
- 19.2.6T7 Application of Maclaurin's theorem in numerical work.

Suggested teaching/Learning Resources

- Laplace transform reference table

19.2.6 POWER SERIES

- 19.2.6T0 *Specific Objectives*
By the end of the sub-module unit, the trainee should be able to:
- a) explain the term power series.
- b) state Taylor's theorem without reminder.

19.2.8 STATISTICS

Theory

- 19.2.8T0 *Specific Objectives*
By the end of the sub-module unit, the trainee should be able to:
- a) Organize and present data coefficient

	b) determine measures of central tendencies for data		- Calculation of correlation
	c) determine measures of dispersion	19.2.9	PROBABILITY
	d) define skewness		Theory
	e) determine the coefficient of skewness	19.2.9T0	<i>Specific Objectives</i> By the end of the sub - module unit, the trainee should be able to:
	f) define regression lines		a) define concept of probability
	g) define correlation coefficients		b) identify various types of events
	<i>Content</i>		c) state laws of probability
19.2.8T1	Data organisation		d) describe types of data distribution
	i) Frequency distributions and diagrams		e) define Theorems of Mathematical expectations
	ii) Grouped and ungrouped		f) describe sampling methods
19.2.8T2	Determination of measures of central tendencies		
	i) Mean		<i>Content</i>
	ii) Median	19.2.9T1	Probability random variable
	iii) Mode	19.2.9T2	Types of events
19.2.8T3	Measures of dispersion	19.2.9T3	Laws of probability
	i) Range	19.2.9T3	Theorems on expectation
	ii) Mean	19.2.9T4	Types of data distributions
	iii) Deviations		i) Poisson distribution
	iv) Variance		ii) Binomial distribution
	v) Standard deviation		iii) Continuous distributions
19.2.8T4	Definition of skewness		iv) Normal distribution
	• Pearson's coefficient of skewness		v) T-distribution
19.2.8T5	Coefficient of skewness		vi) Chi-Square distribution
	i) Negative		vii) Interpretation of their tables
	ii) Zero		
	iii) Positive		
19.2.8T6	Definition of regression lines		
19.2.8T7	Definition of correlation coefficients		
	- Calculation of regression lines		

viii) Application of various distribution methods

ix) confidence limits of mean and difference of means

x) Tests of hypothesis

xi) Goodness of fit

19.2.9T5 Sampling methods

i) Sampling distribution

ii) Applications

Suggested teaching/Learning Activities

- Discussion
- Illustration
- Demonstration

Suggested teaching/Learning Resources

- Advanced Mathematical tables
- Scientific calculator

Suggested Evaluation Methods

- Oral tests
- Timed written tests
- Assignments

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